

# SEN9110 Simulation Masterclass

## Lecture 6. Object-Oriented Simulation

Prof.dr.ir Alexander Verbraeck  
a.verbraeck@tudelft.nl

Brightspace: SEN9110

# Agenda of this lecture

- Final questions about DEVS paradigm
- Questions about object-oriented papers
- Principles of object-orientation
- Object-orientation in simulation
- Example: DSOL

# 1.

---

## Principles of object-orientation

---

# Object Orientation: what is it?

- Object Orientation is a **modeling approach** [Booch:1999]
- We **choose** to see the world object oriented because it helps us to understand the systems we are designing and analyzing
- Choosing an OO-approach has strong **consequences** (our promise: you will never be able to see the world not-OO based again)

# Characteristics of an object

- **Identity:** you can name an object or distinguish it from other objects
- **State:** the state of an object is defined by its attributes (i.e. age, speed, weight, size, etc.)
- **Behavior:** you can do things to the object (invoke its methods) and the object can invoke methods on other objects.

# Objects as the basis for OO approach

source: msnbc website



Object: a traffic jam



Object: a car



Object: a tire

# Principles of object orientation (1 / 9)

## 1. The ability to specify classes

- Modeling perspective: template for a type of objects
- Design perspective: a class is just another object
- Implementation perspective: global object

# Principles of object orientation (2/9)

## 2. Information hiding

- An object explicitly describes which attributes are publicly visible and therefore accessible
- Public, protected and private modifiers enable information hiding

# Principles of object orientation (3/9)

## 3. Encapsulation

- Attributes and methods uniquely belong to an object
- No need to check access! Access is controlled in the class

# Principles of object orientation (4/9)

## 4. Polymorphism

- A programming language's ability to process objects differently depending on their class. The ability to redefine methods for derived classes.

# Principles of object orientation (5/9)

## 5. Inheritance

- Classes can be organized in a hierarchical structure. In such a structure the subclass inherits the **protected and public attributes and methods from the superclass.**

# Principles of object orientation (6/9)

## 6. Delegation

- An object passes the invocation of a method on to another object that actually fulfils the invoked method

# Principles of object orientation (7 / 9)

## 7. Asynchronous communication

- An object invokes a method on another object where it does not expect immediate result

# Principles of object orientation (8/9)

## 8. Late binding (or dynamic or run-time binding)

- Support for the ability to determine the specific class and thus the specific specification at runtime. This mechanism enables polymorphism.

# Principles of object orientation (9/9)

## 9. Design by contract

- The ability to design a set of methods as a contract via the usage of interfaces.

# Classes as templates for objects

- **Classes** are the most important building block of any object-oriented system.
- A **class** is a template for a set of objects that share the same attributes (defining their state), operations, relations and semantics.

# The illustration of a class

Computer
processor memory keyboard
reset() shutdown() start()

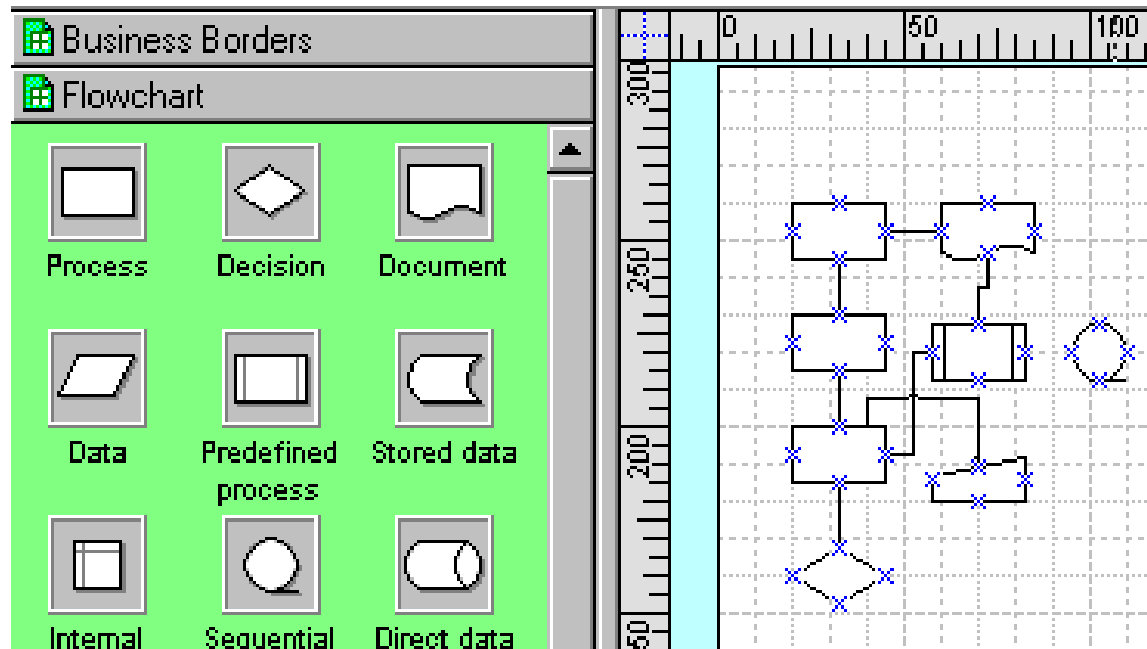
name

attributes  
(called fields in Java)

methods

# Instantiate objects from a class

Analogous to instantiating a shape in Visio:



# Class libraries

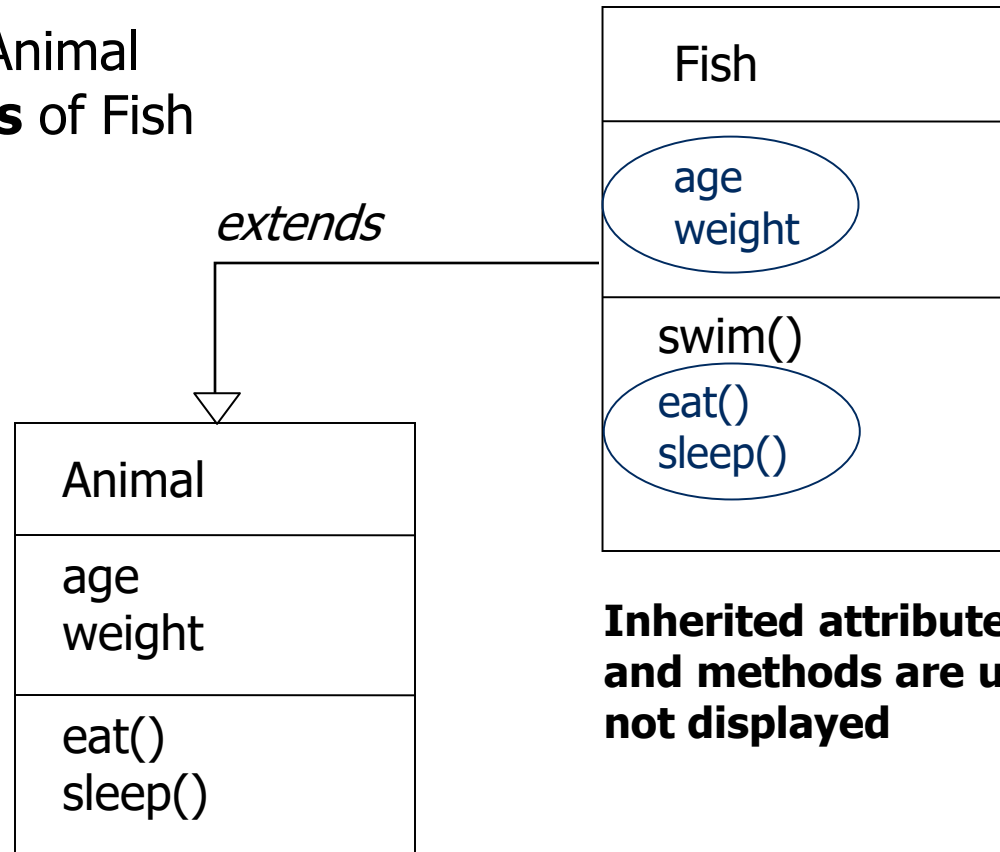
- `nl.abnamro.management.Chair` class versus `nl.pastoe.furniture.Chair`
- **Libraries** group a logical set of classes. Statistical library, graph library, hi-speed math library, supply chain library, automated guided vehicle library

# Classes : subclass & superclass

- A **subclass** is a specification of a class. We design a subclass whenever extra operations, relations or attributes describe a subset of objects. Fish **is** a subclass of Animal **when** we define the operation swim().
- A **superclass** is the more general “parent” class from which operations, methods and relations are **inherited**

# Classes: subclass & superclass

Fish is a **subclass** of Animal  
Animal is a **superclass** of Fish

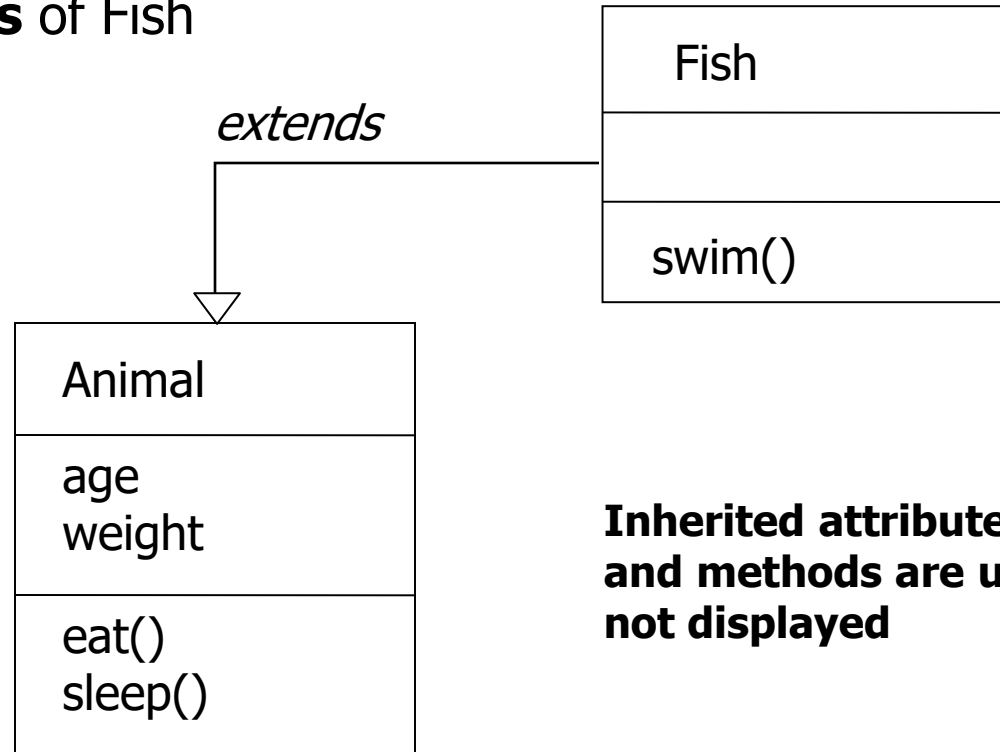


**Inherited attributes and methods are usually not displayed**

# Classes: subclass & superclass

Fish is a **subclass** of Animal

Animal is a **superclass** of Fish



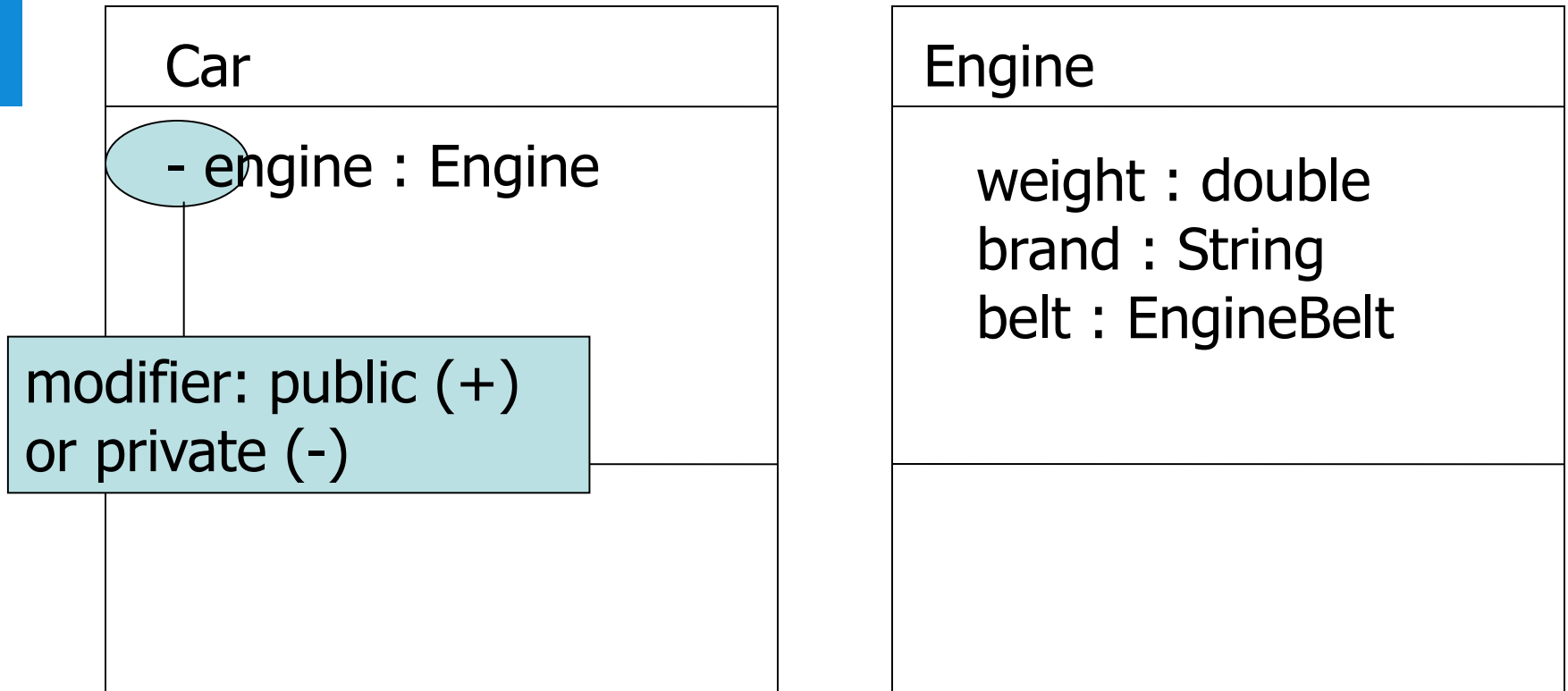
**Inherited attributes  
and methods are usually  
not displayed**

# Classes and their relations (1 / 10)

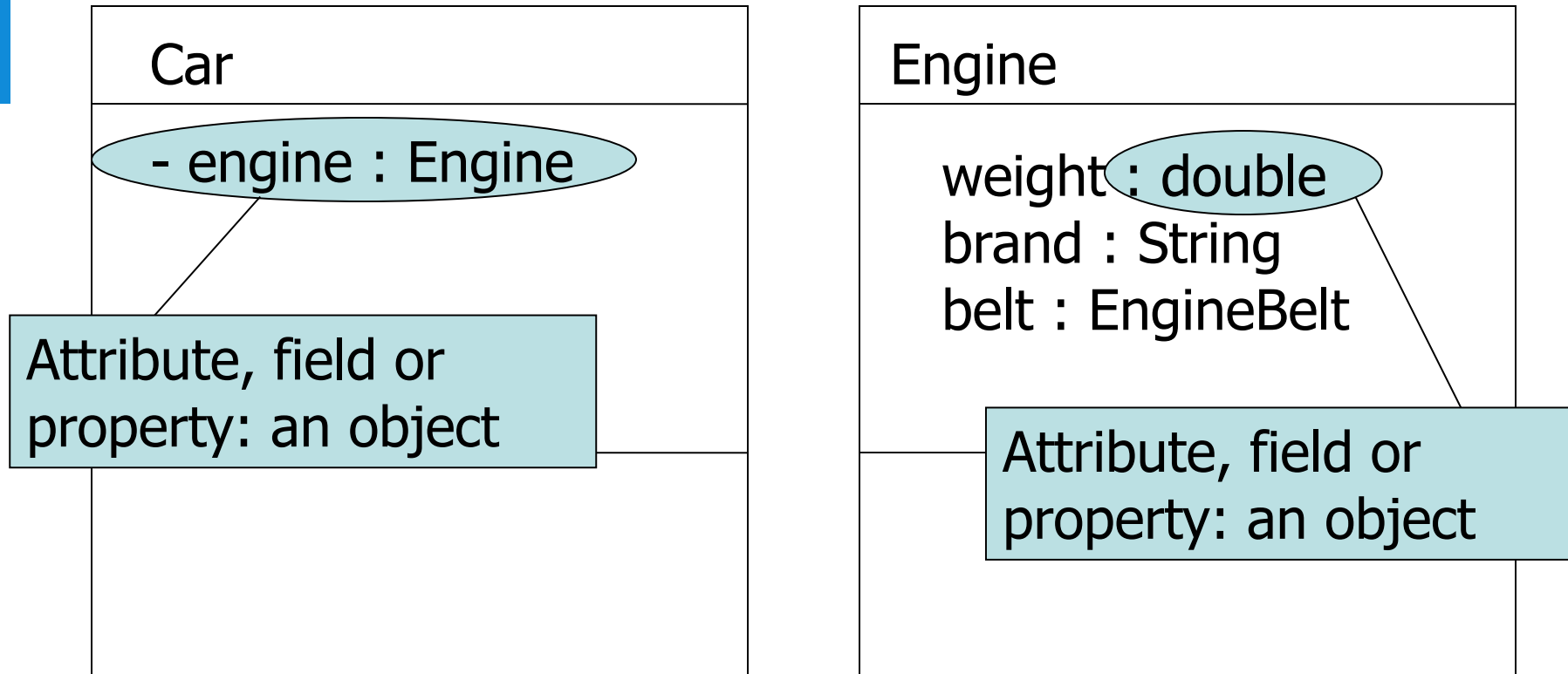
Car
- engine : Engine

Engine
weight : double brand : String belt : EngineBelt

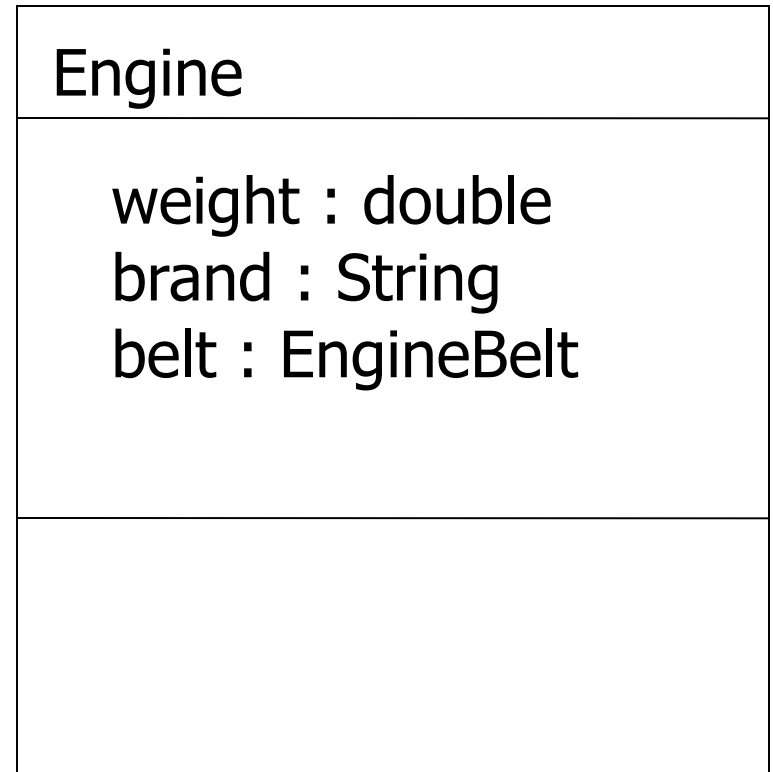
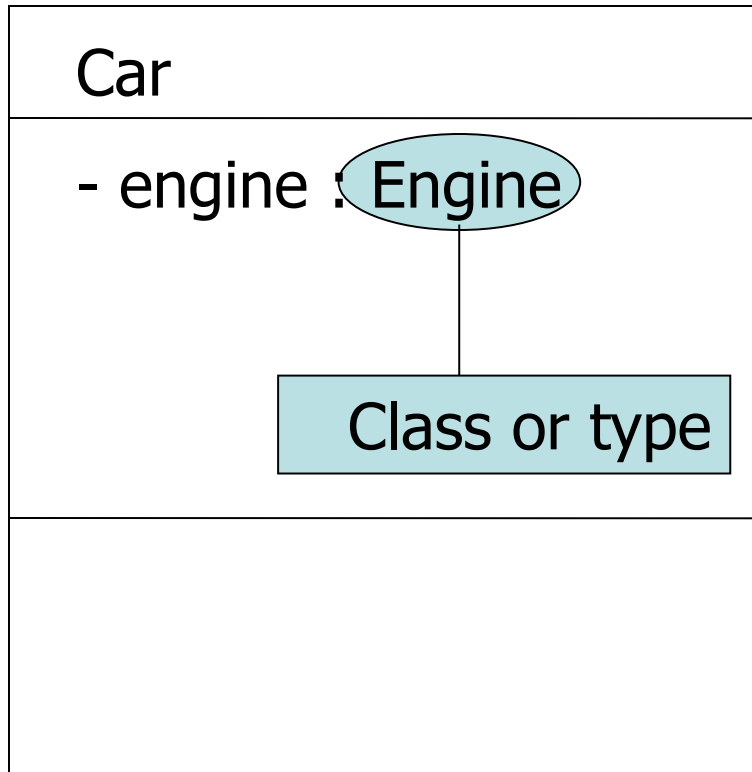
# Classes and their relations (2 / 10)



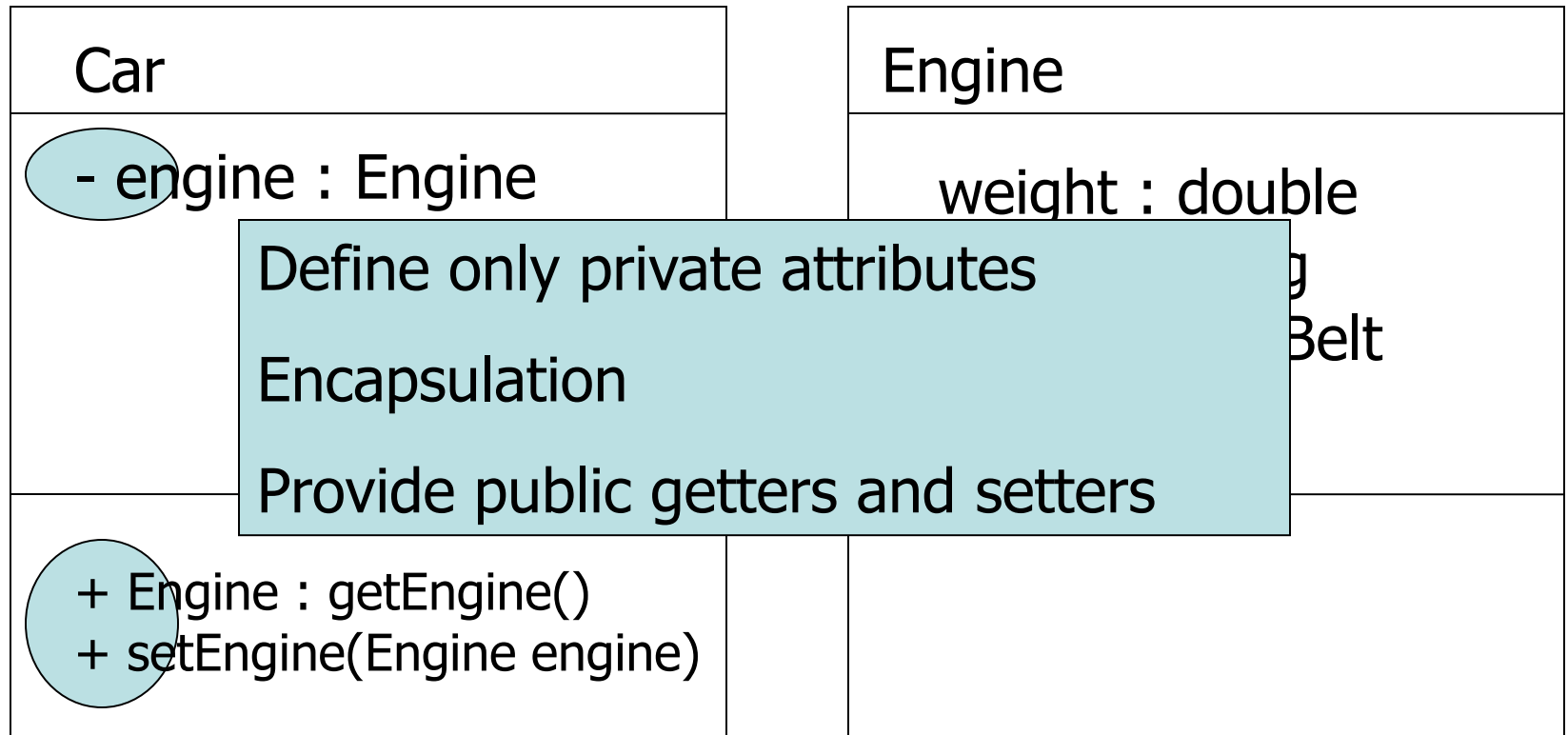
# Classes and their relations (3 / 10)



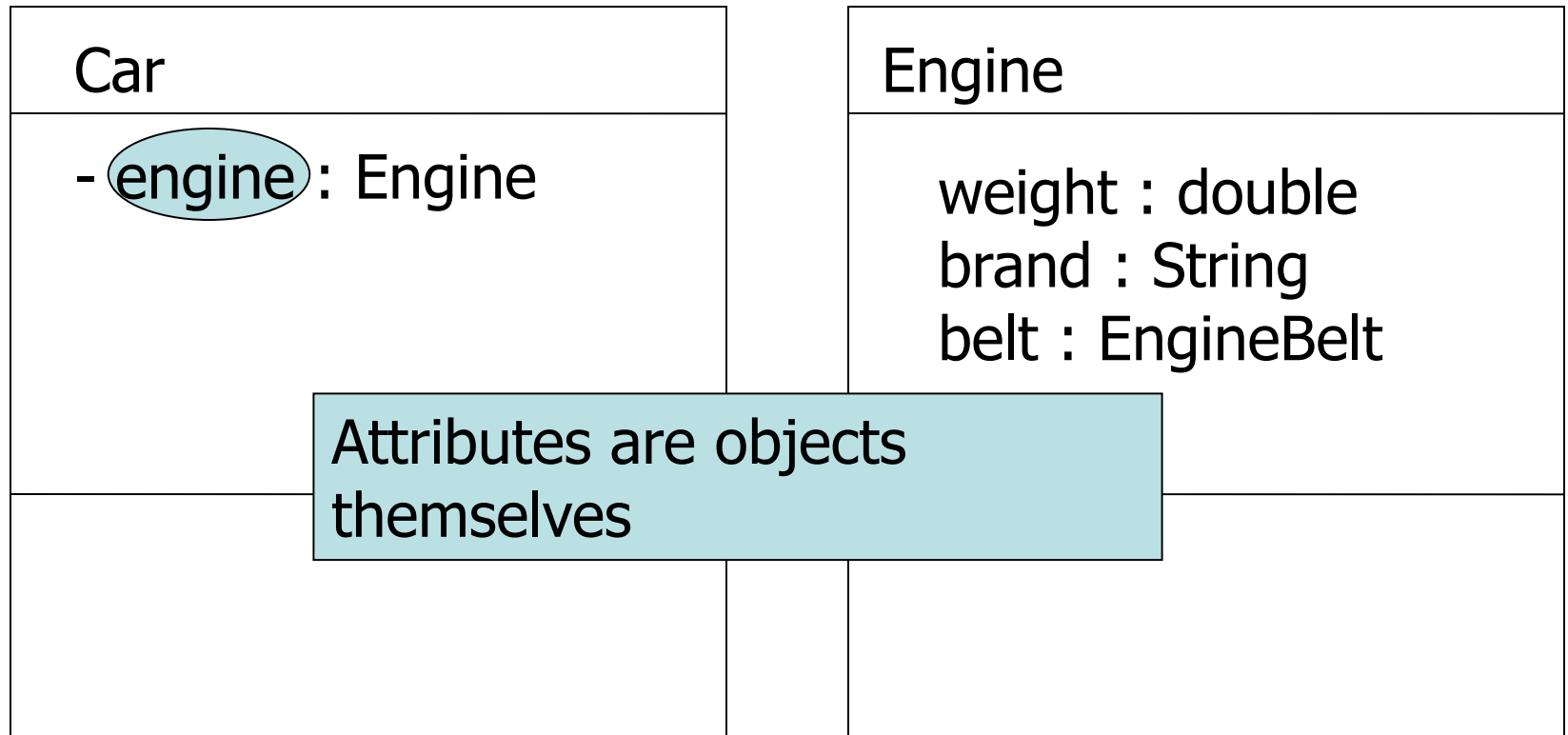
# Classes and their relations (4 / 10)



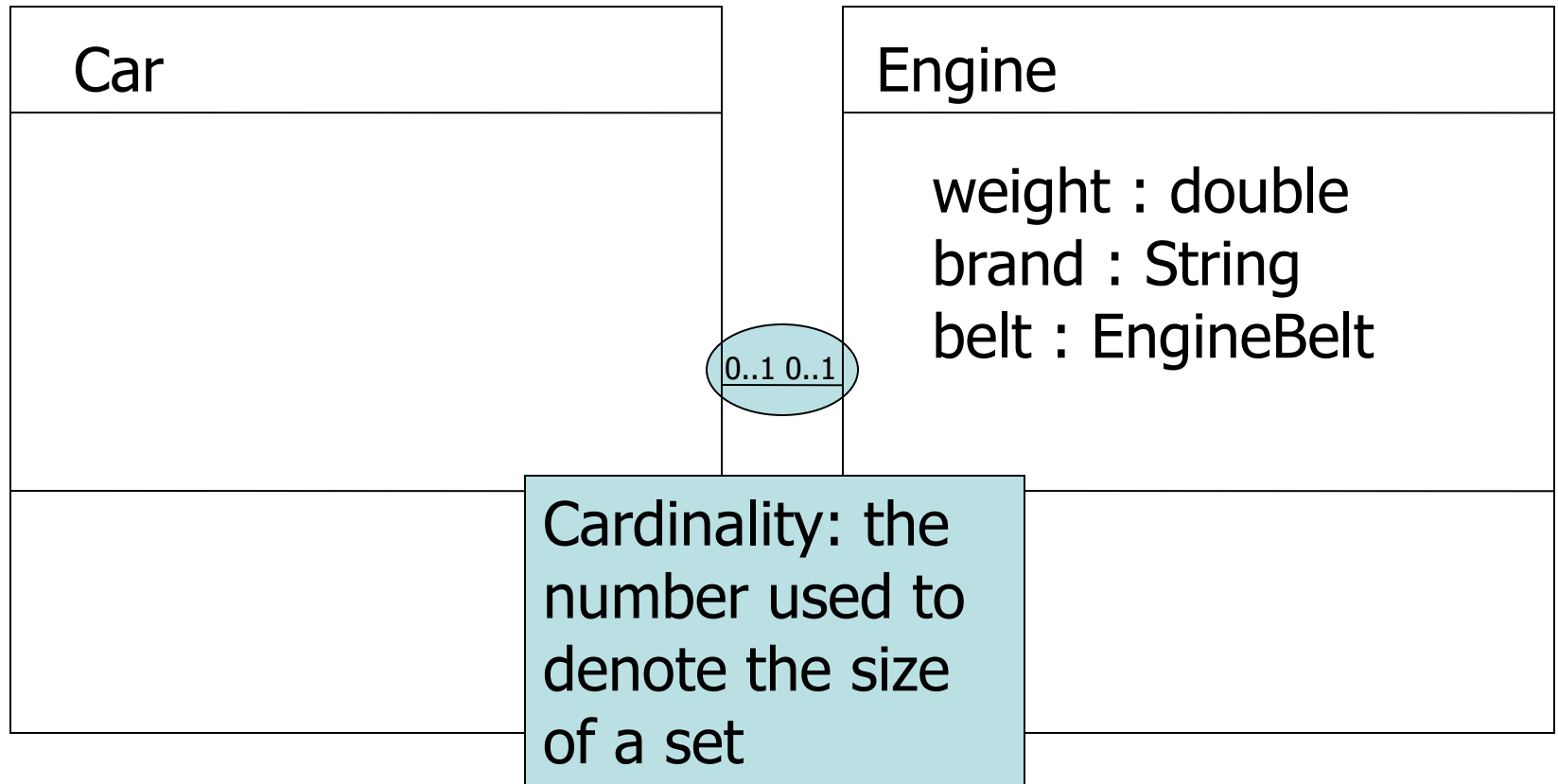
# Classes and their relations (5 / 10)



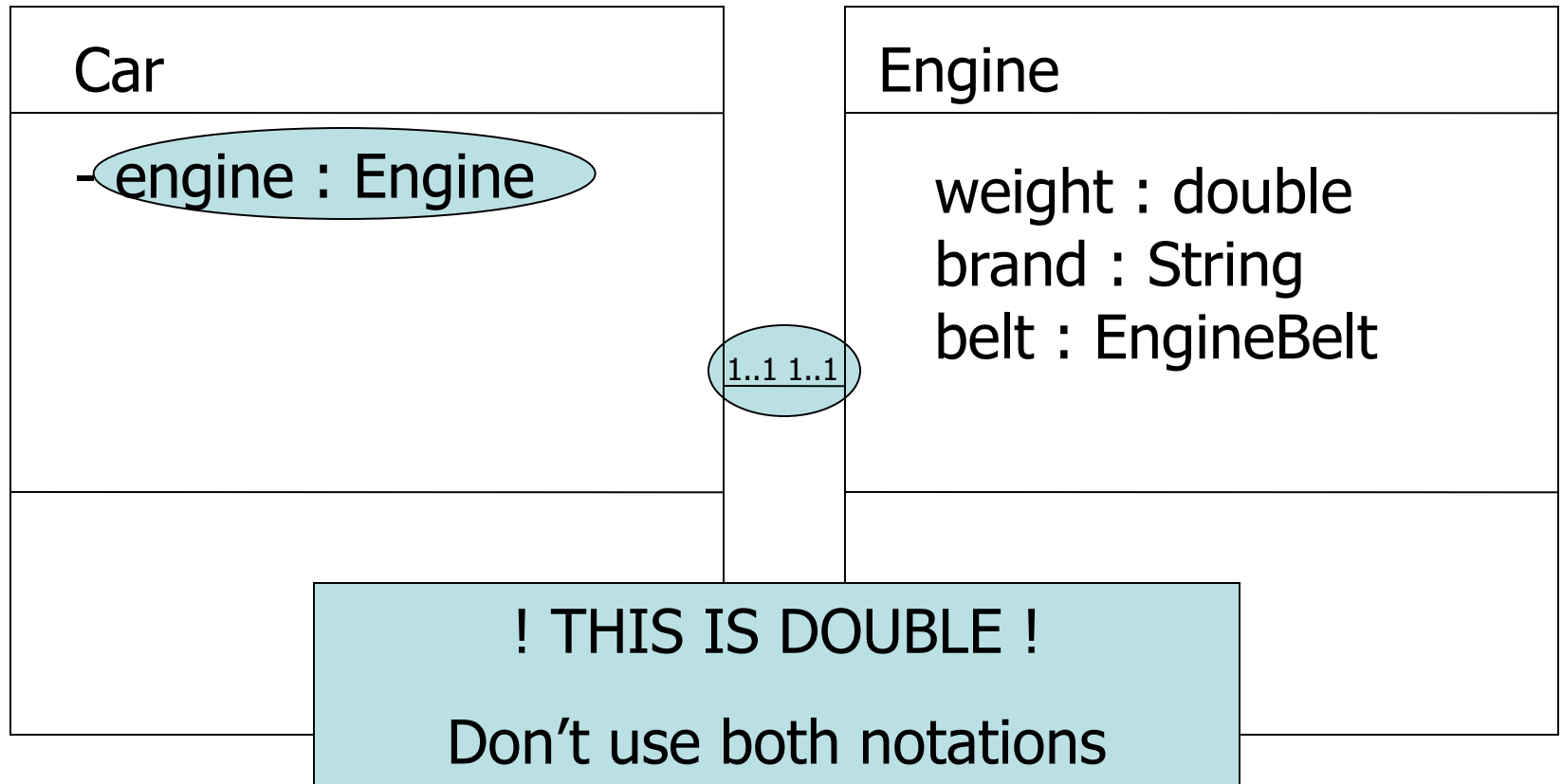
# Classes and their relations (6 / 10)



# Classes and their relations (7 / 10)



# Classes and their relations (8/10)



# Classes and their relations (9 / 10)

- **Aggregation** : a car physically consists of an engine, tires, steering wheel, etc.
- **Association**: a newspaper and a customer are associated by a subscription
- In OO languages such as Java there is (often) **NO DISTINCTION** between aggregation and association
- This is a **BIG PROBLEM** for simulation
  - WHY?

# Classes and their relations (10/10)

## Polymorphism

Calculator
+ add(double a,double b) + add(int a,int b)

**Polymorphism** enables the distinction of method invocation based on different 'signatures'

**Polymorphism** is method overloading

Be smart! It helps preventing redundant specification

# 2.

---

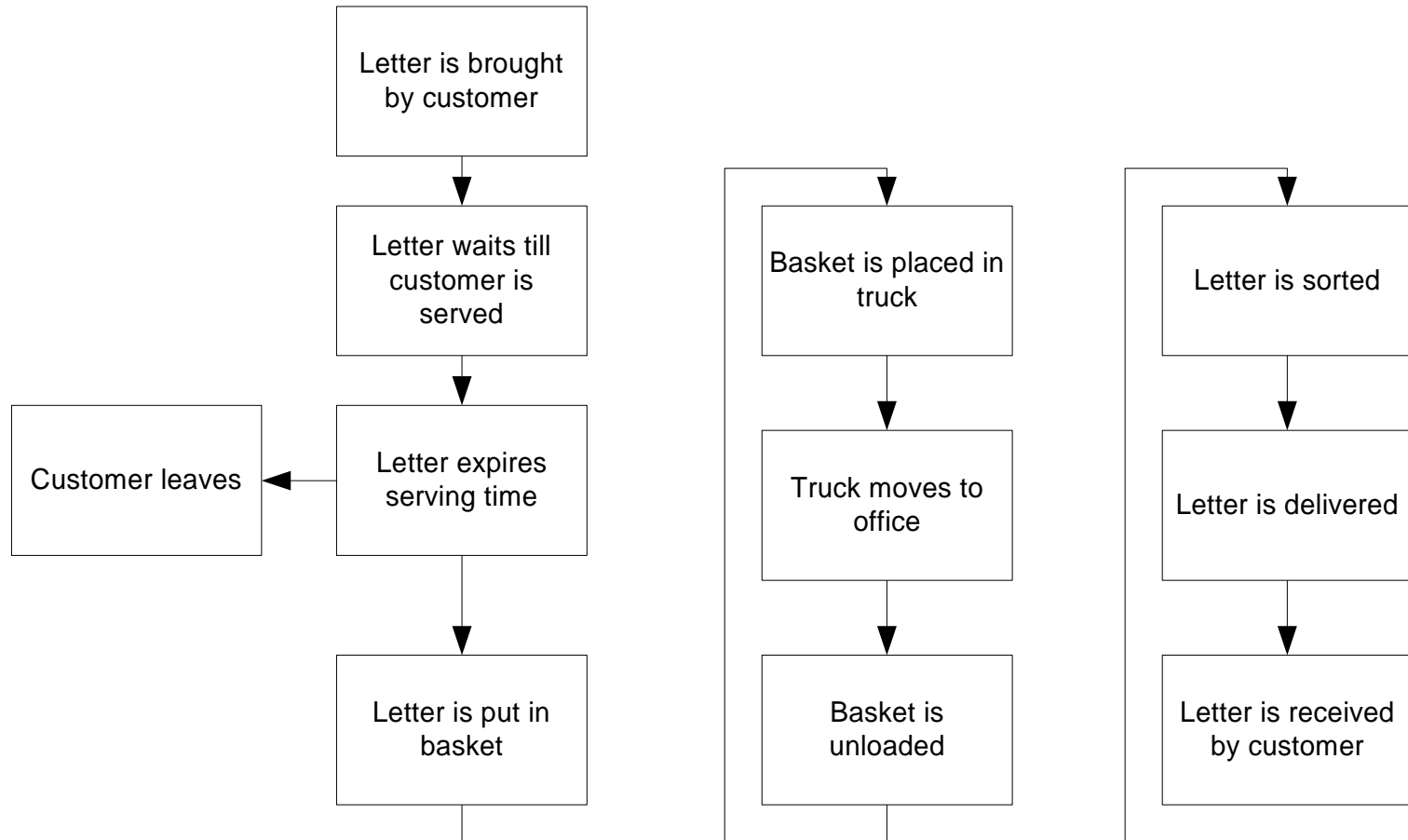
## Object orientation in Simulation

---

# Simulation models

- Models are described in several formalisms. How do they relate or comply with OO?
- Flow based models (Arena)
- Activity based models
- Arena is coded in C++, an object-oriented language. Same for Simio, which is coded in C#. Are their models therefore OO?

# A flow based overview of posting a letter (1 / 5)



## OO based specification of posting a letter (2/5)

We create instances for our simulation model. See the difference between instances and classes.

**(Capital S, C, P means class, small s, c, p means instance)**

Simulator simulator = new Simulator()

Customer customer = new Customer()

Postbox postbox = new Postbox()

Postman postman = new Postman()

PostOffice postOffice = new PostOffice()

## OO based specification of posting a letter (3/5)

- simulator → customer.moveTo(postbox)
- customer → postbox.receive(letter)
- simulator → postman.moveTo(postbox)
- postman → postbox.empty()
- postman → this.moveTo(postOffice)
- postman → postOffice.receive(collectedLetters)

## OO based specification of posting a letter (4/5)

**simulator** → customer.moveTo(postbox)  
customer → postbox.receive(letter)

**simulator** → postman.moveTo(postbox)  
postman → postbox.empty()  
postman → this.moveTo(postOffice)  
postman → postOffice.receive(collectedLetters)

Event scheduling in a  
simulation

## OO based specification of posting a letter (5/5)

- simulator → customer.moveTo(postbox)
- customer → postBox.**receive**(letter)
- simulator → postman.moveTo(postbox)
- postman → postbox.empty()
- postman → this.moveTo(postOffice)
- postman → postOffice.**receive**(collectedLetters)

Postbox and PostOffice both implementing a receiver

# 3.

---

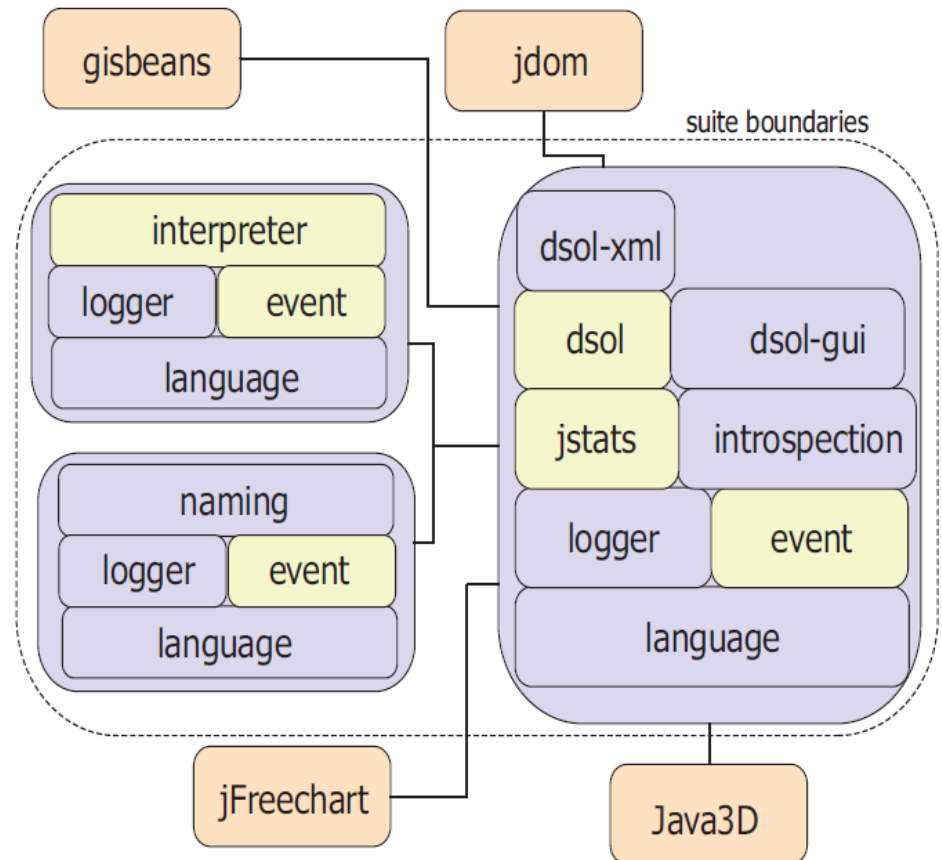
## Object orientation in Simulation Languages: DSOL

---

# Aims of this part of the presentation

Discuss the 3 main requirement

- **Distributing** the framework for modeling and simulation
- Providing enough **formalisms** for the construction of models
- Implements DSOL in a **service oriented** architecture



# The problems we aim at in modern simulations:

- Multiple **distributed** stakeholders
- System conceptualization in a **system** of models
- System specification is tightly linked with **underlying IT infrastructure**
- **Collaborative** model construction and problem solving
- The construction of **complex** models, in terms of time, aspects and scope

# A vision on service based simulation (1)

## Current simulation tools

1 stakeholder is locally supported by a simulation study

1 model formalism is allowed in a simulation study

1 simulation expert can simultaneously work on a simulation model

## Service based simulation

N stakeholders are web-enabled and simultaneously supported

N formalisms can be used to express parts of the model

N simulation experts can collaboratively work on a model

# A vision on service based simulation (2)

## Current simulation tools

1 set of tools can be used for reporting, animation, etc. etc.

1 processor can be used to deploy the simulation model

monolithic models are developed, globally accessible members

## Service based simulation

N services can interact to present, report, compute the study

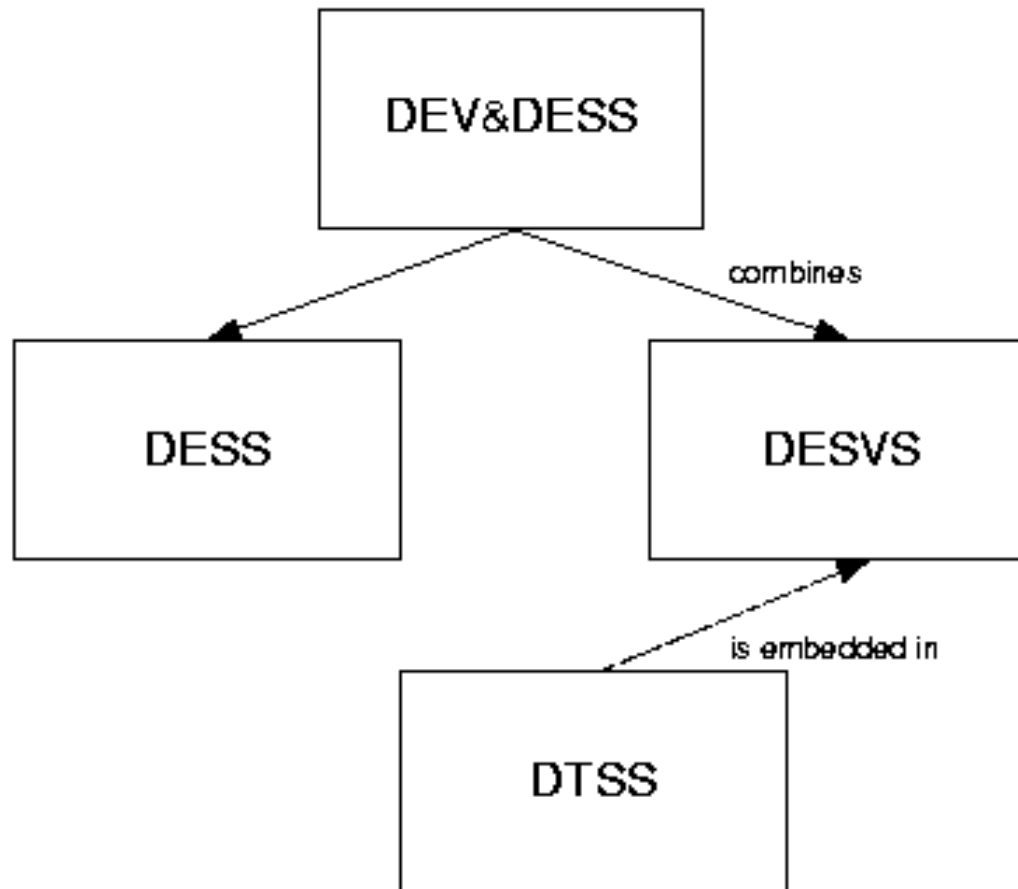
N computational processors can be used to deploy models, services and simulators

modular models are developed, encapsulated members

# Distribution in the framework for M&S.

- Distributed DSOL **application**: Open remote experiments, report to the web, view animation remotely. Supported in DSOL : **YES!**
- Distributed **model** specification: Entity and simulator distributed, customer and resource distributed, etc. Supported in DSOL : **YES!**
- Distributed **simulator**: HLA / IEEE 1516, time synchronization between simulators. Supported in DSOL : **YES!**

# Formalisms in the framework for M&S



# Relations between formalisms

- **Combining** relation : A combines B and C whenever B and C in A
- **Embedding** relation: A embeds B whenever any model expressed in B can be expressed in A
- **Root formalism**: there is no formalism which can be embedded by root formalism A

See also the papers from Vangheluwe & De Lara that we will cover for multi-paradigm simulation.

# Formalisms in DSOL

- DEV&DESS root formalisms is supported by a unique simulator. This **guarantees** multiformalism!
- Several non-root formalisms are nevertheless supported with unique simulator for **performance optimization**. (DESS, DEVS)
- Several non-root formalisms are supported by libraries **embedding** the formalism (Flow is embedded in DEVS)

# Service oriented system design (I)

- **Object orientation** is the de facto modeling and programming language for the design of information systems
- A **service** is a **contractually** defined behavior that can be implemented and provided by any component for use by any other component, based solely on the contract. This contract is also referred to as the **interface** of a service

# Service oriented system design (II)

- The **encapsulation** of states. Since a service only describes methods, the state of a component providing the service is shielded to those components invoking it
- The prevention of relations between objects or components. Service oriented design encourages objects to relate to an **interface**. Whenever the particular specification or embodiment of the service changes, this has no consequences for the relation
- **Collaborative** system specification. Whenever the interfaces of a system are designed, several engineers can collaboratively and concurrently implement parts of the system without potential integration problems

# DEVS implementation of event scheduling

- Delayed method invocation
- Any method can be called based on a delay relative to the time base

```
simulator.scheduleEvent(delay, class, "methodName", arguments);
```

```
private startService() {  
    double hour = TimeUnit.convert(simulator, 1.0, TimeUnit.HOURS);  
    simulator.scheduleEvent(hour, this, "serviceReady", null);  
}
```

```
private newCustomer() {  
    Customer customer = new Customer(simulator);  
    DistContinuous interArrivalTime = new DistExponential(5.0);  
    double iat = TimeUnit.convert(simulator, interArrivalTime.draw(),  
        TimeUnit.MINUTE);  
    simulator.scheduleEvent(iat, this, newCustomer, null);  
}
```

# Conclusions

- DSOL is a Java-based distributed application, with pyDSOL containing a Python version of DSOL
- DSOL is an object-oriented simulation framework for distributed modeling
- DSOL supports several formalisms among which: DESS, DEVS, DTSS, DEV&DESS, DSDEVS, QDEVS
- DSOL and pyDSOL are open source and published under BSD on github